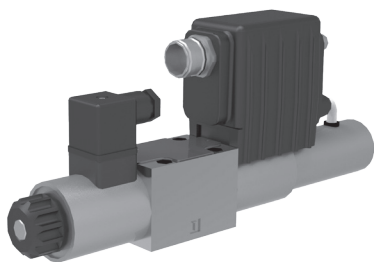


**Technical Features**


- › Direct acting, proportional control valve with integrated digital electronic (OBE) proportional control, spool and process feedback
- › Control valve with subplate mounting surface acc. to ISO 4401, DIN 24340 (CETOP 03) standards
- › The valve opening and resulting flow rate can be modulated continuously in proportion to the reference signal
- › Digital converter card allows fine control of the valve spool position, reducing hysteresis and response time and optimizing the performance of the valve
- › Various models with or without onboard digital converter card or position sensor feedback available
- › Used for directional and speed control of hydraulic actuators
- › Wide range of interchangeable spools available
- › For versions without OBE wide range of solenoid electrical terminal versions available
- › The driver directly manages digital settings. It's possible to customize the settings for special applications using the optional kit.
- › In the standard version, the valve housing is phosphated and steel parts zinc-coated for 240 h protection acc. to ISO 9227
- › Enhanced surface protection for mobile sector available (ISO 9227, 520 h salt spray)

**Functional Description**

The proportional directional valve PRM7 consists of a cast iron housing, a special control spool, two centering springs with supporting washers, one or two proportional solenoids, a position sensor or, if need be, of a control box with digital electronics. The measuring system of the position sensor consists of a differential transformer with core and from the evaluating electronic unit realized in hybrid technique.

**Models without integrated electronic unit OBE**

The electrical connection of the solenoids is realized by a variety of connectors. The position sensor output is connected by the G4W1F connector plug. Both connectors are supplied.

In this case the proportional valve can be used as follows:

**S01, S02** with the internal feedback from the spool position sensor.

**Models with the integrated electronic unit OBE**

The model comprises an electronic control box that is mounted together with the position sensor on either of the solenoids. The connection of the position sensor to the control box is provided by a cable. For models with two solenoids, the solenoid mounted opposite the control box is connected to the control box by a EN 175301-803 connector.

The connection of the supply voltage, control signal, program input and external output of the position sensor is implemented in a 5-pin connector (ELKA 5012). The connection of the external feedback is provided by a 5-pin connector, which also has three supply voltages +24 V, +10 V and -5 V for an external sensor available.

The solenoid coils, including the control box, can be turned in the range of  $\pm 90^\circ$ . The digital control unit enables the proportional valve to be controlled on the basis of data required from two feedback circuits. In this case the proportional valve can be used as follows:

**E01** Proportional directional valve

**E02\*S01** Only with the internal feedback from the spool position sensor.

**E03** Only with the external feedback (pressure sensor, position sensor, etc.).

**E04\*S01** With internal and external feedback.

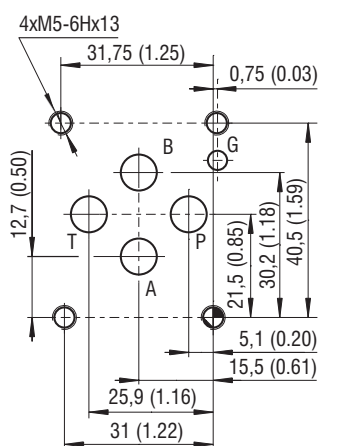
The digital control unit utilizes pulse-width-modulation (PWM) and supplies the solenoids with current proportional to the control signal.

The supply current is additionally modulated with a dither frequency. Individual functional parameters are adjusted through software by a special programmer, or by computer through the RS 232 interface. The cable kit must be ordered separately, as detailed on page 4. The correct function of the digital control unit is signaled by a green LED. The incorrect function (failure) is indicated by a red LED. As a standard, the proportional valve is delivered with factory setting.

For a model including an external feedback contact the manufacturer.

## Technical Data

### ISO 4401-03-02-0-05



Ports P, A, B, T - max Ø7.5 mm (0.29 in)

Valve Size		06 (D03)
Max. operating pressure at ports P, A, B	bar (PSI)	350 (5100)
Max. operating pressure at port T	bar (PSI)	210 (3050)
Fluid temperature range (NBR)	°C (°F)	-30 ... +80 (-22 ... +176)
Fluid temperature range (FPM)	°C (°F)	-20 ... +80 (-4 ... +176)
Ambient temperature max.	°C (°F)	-30 ... +50 (-22 ... +122)
Nominal flow $Q_n$ at $\Delta p=10$ bar (145 PSI)	l/min (GPM)	5 (1.3), 8 (2.1), 15 (4.0), 30 (7.9)
Hysteresis	%	< 6
Hysteresis - closed position loop	%	< 0.5
Protection degree EN 60529		IP65
Mass	kg (lbs)	- valve with 1 solenoid: 2.3 (5.1) - valve with 2 solenoids: 2.8 (6.2)
Data Sheet		Type
General information	GI_0060	Products and operating conditions
Coil types / Connectors	C_8007 / K_8008	C22A* / K*
Mounting surface	SMT_0019	Size 06
Spare parts	SP_8010	
Subplates	SP_0002	DP*-06

## Ordering Code

**PRM7-06** / [ ] - [ ] [ ] [ ] [ ] - [ ]

**Proportional directional control valve, with digital control electronics, feedback and OBE**

**Valve size**

**Spool symbols**  
see the table „Spool symbols“

**Nominal flow rate at  $\Delta p = 10$  bar (145 PSI)**

flow 5 l/min (1.3 GPM)	<b>5</b>
flow 8 l/min (2.1 GPM)	<b>8</b>
flow 15 l/min (4.0 GPM)	<b>15</b>
flow 30 l/min (7.9 GPM)	<b>30</b>

**Nominal solenoid supply voltage**

12V DC	<b>12</b>
24V DC	<b>24</b>

**No designation**

**Surface treatment**

No designation	Standard
A	240 h salt spray test (ISO 9227)
B	520 h salt spray test (ISO 9227)

**No designation**

**Seals**

No designation	NBR
V	FPM (Viton)

**No designation**

**Installation side of OBE and position transducer**

No designation	OBE with spool position transducer at side of port A
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**Model**

S01	position sensor with voltage outlet
S02	position sensor with current outlet
E01	proportional directional valve without feedback
E02S01	proportional directional valve with position feedback
E03	proportional directional valve with external feedback
E04S01	proportional directional valve with position and external feedback

- For proportional valves with two solenoids, one solenoid must be de-energized before the other solenoid can be charged.
- Mounting bolts M5 x 45 DIN 912-10.9 or studs must be ordered separately. Tightening torque is 8.9 Nm (6.56 ft-lbf)
- Besides the shown, commonly used valve versions other special models are available.
- Contact our technical support for their identification, feasibility and operating limits.

## Spool Symbols

Type	Symbol	Type	Symbol
2Z51		3Z11	
2Z11		3Z12	
2Y51		3Y11	
2Y11		3Y12	

$q_A = \frac{1}{2}$

$q_B = \frac{1}{2}$

\*Model for cylinders with asymmetric piston area ratio 1:2

### Technical Data of Position Sensor - Voltage Outlet

Operating pressure	bar (PSI)	to 350 (5100), static
Electrical connection * only for S01 model		electrical connector G4W1F Hirschmann*
Contact assignment		1 - Power supply 2 - Command signal 3 - GND 4 - not used
Enclosure protection type according to EN 60529		IP65
Measured distance	mm (in)	8 (0.315)
Operating voltage	V	9.6 ... 30 DC
Linearity error	%	< 1
Current consumption at load current of 2 mA	mA	< 15
Output voltage	V	0 ... 5
Output signal range used: 0 position 1 solenoid - stroke 2.8 mm (0.11 in) 2 solenoids - stroke $\pm$ 2.8 mm (0.11 in)	V	2.5 0.75 ... 2.5 0.75 ... 4.025
Max. load current	mA	2
Noise voltage - at load current 0 - at load current of 2 mA	mV <sub>p-p</sub>	< 20 < 15
Additional output signal error at: - temperature change between 0 ... 80°C (32... 176 °F) - between 0 ... -25 °C (32 ... -13 °F) - Load change from 0 to 2 mA		typical 0.2% / 10K max. 0.5 % / 10K max. 0.5 % / 10K 0.1 %
Input voltage change from 9.6 V to 14.4 V from 14.4 V to 30 V	%	< 0.1 < 0.25
Long-term drift (30 days)	%	< 0.25
Cut-off frequency 3dB fall in amplitude Frequency 90°	Hz	> 600 > 600

### Technical Data of Position Sensor - Current Outlet

Linearity	%	< 1
Operating pressure	bar (PSI)	to 350 (5100), static
Electrical connection * only for S01 and S02 model		electrical connector G4W1F Hirschmann*
Contact assignment		1 - Power supply 2 - Command signal 3 - GND 4 - not used
Enclosure protection type according to EN 60529		IP65
Operating voltage	V	20 ... 30 DC
Current	mA	< 35
Output signal range	mA	4 ... 20
Output signal range used: 0 position 1 solenoid - stroke 2.8 mm (0.11 in) 2 solenoids - stroke $\pm$ 2.8 mm (0.11 in)	mA	12 4.4 ... 12 4.4 ... 19.6
Additional output signal error: - at temperature change from +10 ... 55°C (50... 131°F) - at impedance change from 50% - at input voltage change in the range of operating voltage		0.2% / 10K $\leq$ 0.1% $\leq$ 0.05%
Impedance	$\Omega$	$\leq$ 500
Output signal ripple	mA R.M.S.	$\leq$ 0.02
Limit frequency at 3 dB amplitude decrease	Hz	$\geq$ 800

### Technical Data of Proportional Solenoid

Type of coil	V	12 DC	24 DC
Limiting current	A	2.4	1.0
Resistance at 20 °C (68 °F)	$\Omega$	2.3	13.4

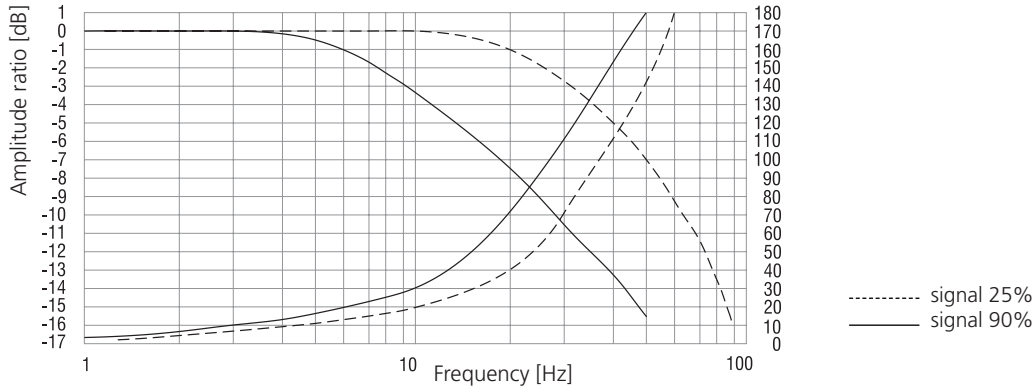
### Electronics Data

Supply voltage with polarity inversion protection	V	11.2 ... 28 VDC (residual ripple < 10%)
Input: command signal / according to customer setting		$\pm$ 10 V, 0...10 V, $\pm$ 10 mA, 4...20 mA, 0...20 mA, 12 mA $\pm$ 8 mA
Input: spool position sensor signal		0...5 V
Input: external feedback signal		0...10V, 4...20 mA, 0...20 mA
Resolution of the A/D converter		12 bit
Output: solenoids		two PWM output stages up to max. 3.5 A
PWM frequency	kHz	18
Adjustment of parameters	$\mu$ S	170
EMC	Interference resistance	61000 - 6 - 2 : 2005
	Radiation resistance	55011 : 1998 class A
Parameter setting	Serial port RS 232 (zero modem). 19200 bauds, 8 data bits, 1 stop bit, no parity. Special software PRM7 Conf.	

### Accessories

Order number	Content
23093400	Connecting cable to PC - length 2 m (6.56 ft), CD-ROM with program PRM7 Conf and user manual
23093500	Connecting cable to PC - length 5 m (16.40 ft), CD-ROM with program PRM7 Conf and user manual
24523400	Connecting cable to PC - length size 2 m (6.56 ft)
24523500	Connecting cable to PC - length size 5 m (6.56 ft)

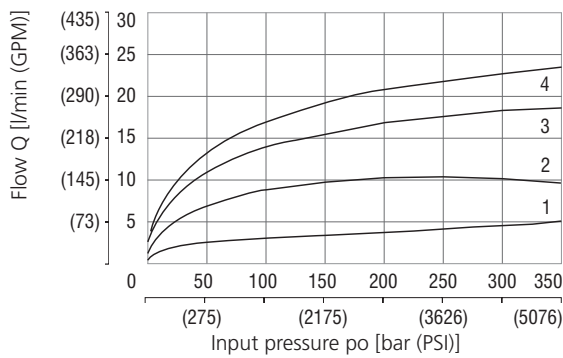
### Frequency Response closed position loop, for E02S01 model



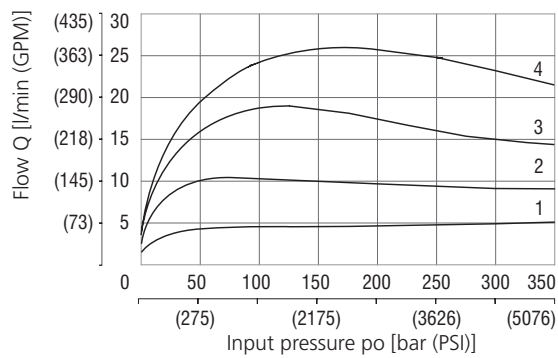
### Characteristics measured at $v = 32 \text{ mm}^2/\text{s}$ (156 SUS)

**Operating limits:** Flow direction P → A / B → T or P → B / A → T  
**Operating limits (E01 model only)**

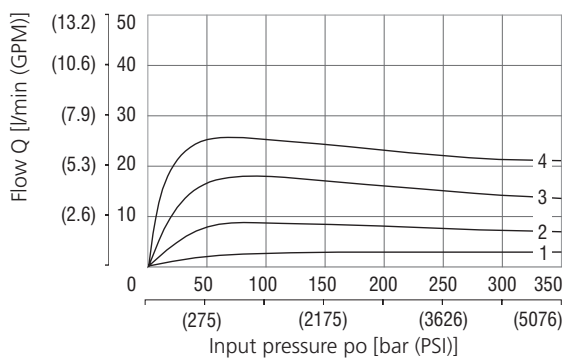
Nominal flow 5 l/min (1.3 GPM)



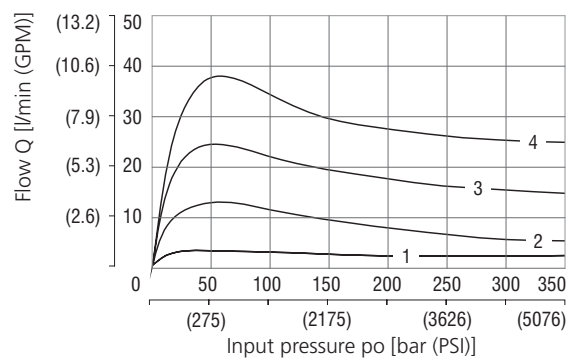
Nominal flow 8 l/min (2.1 GPM)



Nominal flow 15 l/min (4.0 GPM)



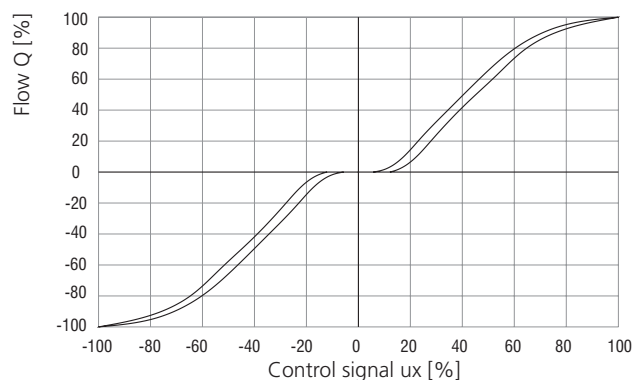
Nominal flow 30 l/min (7.9 GPM)



**Solenoid current:**  
 1 = 50 %  
 2 = 60 %  
 3 = 70 %  
 4 = 80 %  
 5 = 90 %  
 6 = 100 %

### Regulated flow related to control signal

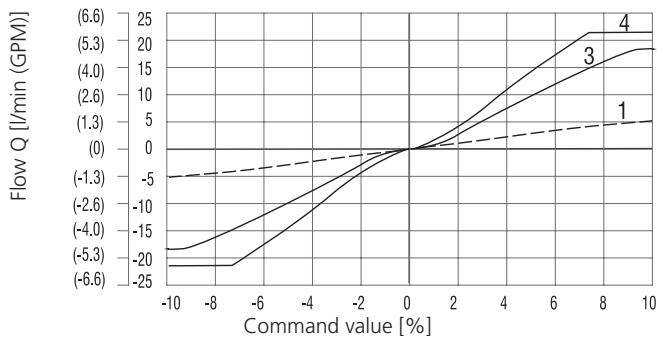
Flow characteristics (E01 model only)  $\Delta p = 10 \text{ bar}$  (145 PSI)



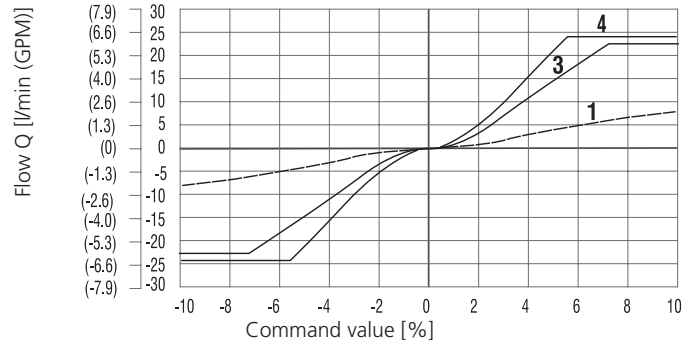
## Flow Characteristics measured at $v = 32 \text{ mm}^2/\text{s}$ (156 SUS)

### Flow characteristics (E02S01 model only)

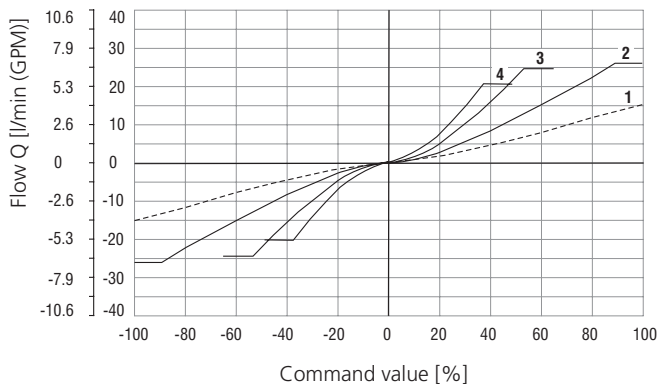
$Q_n = 5 \text{ l/min}$  (1.3 GPM) by  $\Delta p = 10 \text{ bar}$  (145 PSI)



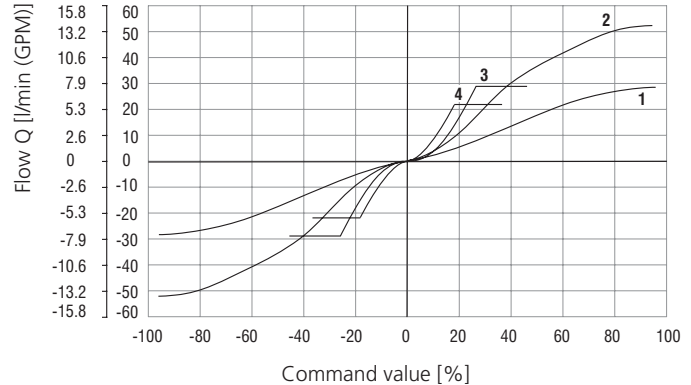
$Q_n = 8 \text{ l/min}$  (2.1 GPM) by  $\Delta p = 10 \text{ bar}$  (145 PSI)



$Q_n = 15 \text{ l/min}$  (4.0 GPM) by  $\Delta p = 10 \text{ bar}$  (145 PSI)



$Q_n = 30 \text{ l/min}$  (7.9 GPM) by  $\Delta p = 10 \text{ bar}$  (145 PSI)



$\Delta p$  = Valve pressure differential (inlet pressure  $p_v$  minus load pressure and return pressure  $p_r$ )

$\Delta p_n$  = Valve pressure differential for nominal flow  $Q_n$

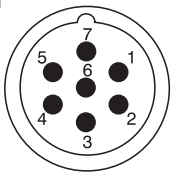
1	$\Delta p_n = 10 \text{ bar}$ (145 PSI)	3	$\Delta p = 160 \text{ bar}$ (2321 PSI)
2	$\Delta p = 50 \text{ bar}$ (725 PSI)	4	$\Delta p = 320 \text{ bar}$ (4641 PSI)

## Factory Settings

Item	Model							
	E01		E02S01		E03		E04S01	
	1 Magnet	2 Magnets	1 Magnet	2 Magnets	1 Magnet	2 Magnets	1 Magnet	2 Magnets
Control signal	0 ... 10 V	$\pm 10 \text{ V}$	0 ... 10 V	$\pm 10 \text{ V}$	0 ... 10 V	$\pm 10 \text{ V}$	0 ... 10 V	$\pm 10 \text{ V}$
Signal external feedback	-		-	-	0 ... 10 V			
Output position sensor spool	-		0 ... 5 V		-		0 ... 5 V	

## Connectors

K1



Connector K1 - type M23 (male)	
PIN	Technical data
1	* Power supply input
2	* Ground (power supply)
3	Control signal
4	Ground (signal)
5	Power reference signal
6	Control signal of position sensor spool
7	* Protective earth lead (PE)

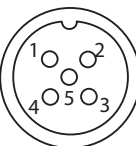
\*Recommended min. lead cross section 0.75 mm<sup>2</sup>

K2



Connector K2 - type M12x1 (male)	
PIN	Technical data
1	TxD
2	RxD
3	Ground (signal)
4	Not used

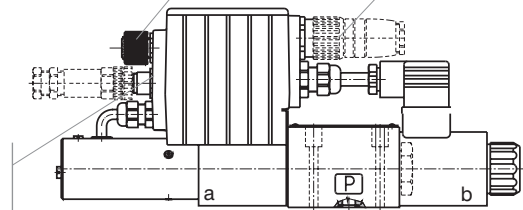
K3



Connector K3 - type M12x1 (female)	
PIN	Technical data
1	Power supply output
2	Signal of external feedback
3	Ground
4	Not used
5	Not used

**K1** - Main input connector M23 (7 PIN)  
Cable diameter 8 ... 12 mm (0.31...0.47 in).

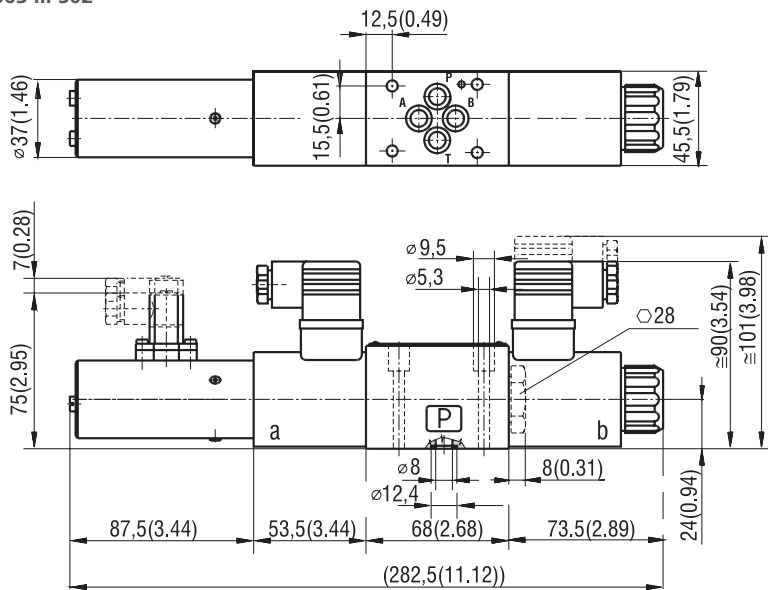
**K2** - Connection RS232 M12x1 (4 PIN)  
To program the electronics.



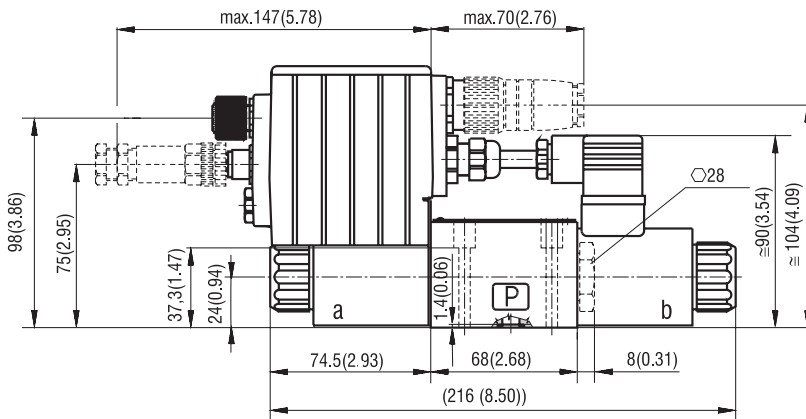
**K3** - Conektor M12x1 (5 PIN)  
External feedback signal (for configurations E03 and E04S01 only).

Dimensions in millimeters (inches)

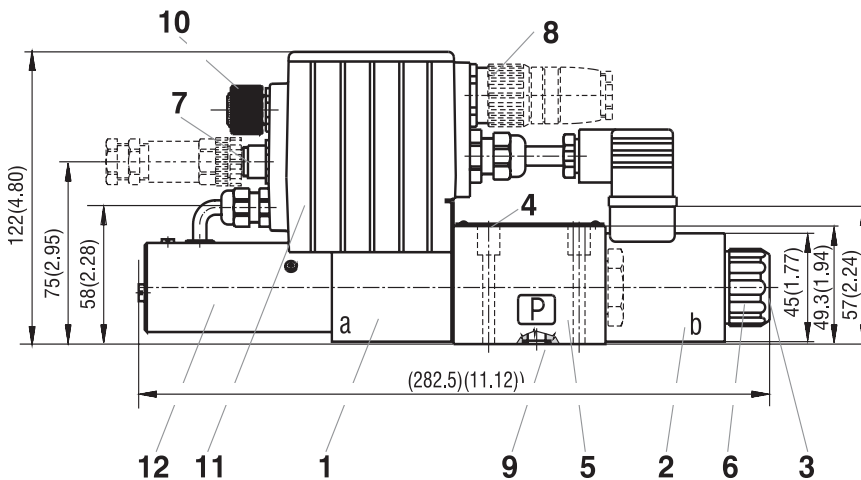
PRM7-063 ... S01  
PRM7-063 ... S02



PRM7-063 ... E01 - without connector plug for spool position feedback  
PRM7-063 ... E03



PRM7-063 ... E02S01 - without connector plug for spool position feedback  
PRM7-063 ... E04S01



- 1 Solenoid a
- 2 Solenoid b
- 3 Manual override
- 4 Name plate
- 5 4 mounting holes
- 6 Solenoid fixing nut
- 7 Connector M12x1 for connection of external feedback
- 8 Main supply connector M23
- 9 Square ring 7.65 x 1.68 (4 pcs.), supplied in delivery packet
- 10 Cover of connector M12x1 for programming
- 11 Plastic box with integrated electronics
- 12 Position sensor